

Vibration Analyst Category I Equations

FORCES

Mass Unbalance

$$F = Me \left(\frac{2\pi N}{60} \right)^2$$

$$M = W/g$$

W = weight of rotor or balance weight, lb

e = rotor eccentricity or radius of balance weight, in

g = gravitational constant, 386.1 in/s²

N = RPM

Spring Force

$$F = Kx$$

K = stiffness of spring, lb/in

x = relative deflection, in

Damping Force

$$F = C \dot{x}$$

C = damping constant, lb-s/in

\dot{x} = relative velocity

Inertia Force

$$F = M \ddot{x}$$

M = mass, lb-s²/in

\ddot{x} = acceleration, in/s²

MOTIONS

Velocity (in/s)

$$V = D(2\pi f)$$

D = peak displacement, in

f = frequency, cycles/s (CPS)

$\pi = 3.14$

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Acceleration

$$A = V(2\pi f)$$

$$A = \text{acceleration, in/s}^2$$

$$1 g = 386.1 \text{ in/s}^2$$

FREQUENCIES

Bearing Frequencies

$$\text{FTF} = \left(\frac{\Omega}{2}\right) \left[1 - \left(\frac{B}{P}\right) \cos CA \right]$$

$$\text{BPFI} = \left(\frac{N}{2}\right) \Omega \left[1 + \left(\frac{B}{P}\right) \cos CA \right]$$

$$\text{BPFO} = \frac{N}{2} \Omega \left[1 - \left(\frac{B}{P}\right) \cos CA \right]$$

$$\text{BSF} = \left(\frac{P}{2B}\right) \Omega \left[1 - \left(\frac{B}{P}\right)^2 \cos^2 CA \right]$$

FTF = fundamental train frequency

BPFI = ball pass frequency, inner race

BPFO = ball pass frequency, outer race

BSF = ball spin frequency

RPM = shaft speed

CA = contact angle

Ω = machine speed

N = number of rolling elements

P = pitch diameter, in

B = ball or roller diameter, in

Bearing defect frequencies are same units as machine speed

General Guideline Bearing Frequencies

(for use in FMax selection ONLY)

$$\text{BPFO} = 0.41 \times \text{RPM} \times N$$

$$\text{BPFI} = 0.59 \times \text{RPM} \times N$$

$$\text{FTF} = 0.41 \times \text{RPM}$$

$$\text{BSF} = 0.22 \times \text{RPM} \times N$$

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Natural Frequency

$$f_n = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

k = stiffness, lb/in

m = w/g

w = weight, lb

g = gravitational constant, 386.1 in/s²

f_n = natural frequency of a single-degree-of-freedom system, Hz

Roll Frequency

$$f = \frac{V}{5\pi D}$$

V = web velocity, ft/min

D = roll diameter, in

f = frequency, Hz

SIGNAL PROCESSING

Dynamic Range

$$\text{dB} = 20 \log \frac{V_m}{V_r}$$

$$\frac{V_m}{V_r} = 10^{\frac{\text{dB}}{20}}$$

V_m = voltage measured

V_r = voltage reference

dB = decibels

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RMS

peak = 1.414 rms

Resolution

Resolution = (frequency span x window noise factor x 2)/#FFT lines

window noise factor =

1.0 for uniform window

1.5 for Hanning window

3.8 for flat top window

Data Acquisition Time (DAT)

DAT = # FFT lines/frequency span

Default Frequency Spans

Operating Speed

= 10 x RPM

Rolling Element Bearings

= 10 x BPFI

Fluid Film Bearings

= 10 x RPM

Vane/Blade Pass

= 3 x # Vanes/Blades x RPM

Electrical

= 3 x 2X Line Frequency

Gear Mesh

= 3 x Gear Mesh Frequency

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